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1 **Evolutionary Algorithm Based Offline/Online Path Planner for UAV Navigation**
*Ioannis K. Nikolos ; Kimon P. Valavanis ; Nikos C. Tsourveloudis ; Anargyros N. Kostaras ;*
Transactions on Systems, Man, and Cybernetics - Part B: Cybernetics : Accepted future publication , 2003
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2 **IEEE standard glossary of computer graphics terminology**
IEEE Std 610.6-1991 , 13 March 1992

[Abstract] [PDF Full-Text (1464 KB)] **IEEE STD**

3 **Hysteresis loss analysis based on W/sub h/-B/sub m/ function**
*Cheng, Z.; Takahashi, N.; Hu, Q.; Fan, C.;*
Computation in Electromagnetics, 2002. CEM 2002. The Fourth International Conference on (Ref. No. 2002/063) , 8-11 April 2002
Page(s): 2 pp.

[Abstract] [PDF Full-Text (250 KB)] **IEE CNF**

4 **TEAM-based benchmark family: Problem 21/21/sup +/ /21**
*Cheng, Z.; Takahashi, N.; Hu, Q.; Fan, C.;*
Computation in Electromagnetics, 2002. CEM 2002. The Fourth International Conference on (Ref. No. 2002/063) , 8-11 April 2002
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1 **Handling complexity in object based modeling and simulation**
*Sharpe, J.E.E.; Bracewell, R.H.;*
Tools for Simulation and Modelling (Ref. No. 2000/043), IEE Seminar on , 27 M
2000
Page(s): 1/1 -1/4

[Abstract] [PDF Full-Text (200 KB)] **IEE CNF**

2 **Robust recognition of calibration charts**
*Soh, L.M.; Kittler, J.;*
Image Processing and Its Applications, 1997., Sixth International Conference o
Volume: 2 , 14-17 July 1997
Page(s): 487 -491 vol.2

[Abstract] [PDF Full-Text (968 KB)] **IEE CNF**

3 **Robust scene interpretation of underwater image sequences**
*Fairweather, A.J.R.; Hodgetts, M.A.; Greig, A.R.;*
Image Processing and Its Applications, 1997., Sixth International Conference o
Volume: 2 , 14-17 July 1997
Page(s): 660 -664 vol.2

[Abstract] [PDF Full-Text (548 KB)] **IEE CNF**

4 **Using eye vergence to interact with objects in the 3-D space created b stereoscopic display**
*Istance, H.; Howarth, P.;*

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*Roberts, M.; Naftel, A.J.;*
Genetic Algorithms in Image Processing and Vision, IEE Colloquium on , 1994
Page(s): 12/1 -12/5

[Abstract] [PDF Full-Text (328 KB)] **IEE CNF**

2 **Three-dimensional echocardiographic reconstruction and geometric a of the human mitral valve**
*Handschumacher, M.D.; Sanfilippo, A.J.; Harrigan, P.; Weyman, A.E.; Levine, R*
Computers in Cardiology 1988. Proceedings. , 25-28 Sept. 1988
Page(s): 19

[Abstract] [PDF Full-Text (48 KB)] **IEEE CNF**

3 **Morphological skeleton transforms for determining position and orien of pre-marked objects**
*Zhou, Z.; Smith, K.C.; Benhabib, B.; Safaee-Rad, R.;*
Communications, Computers and Signal Processing, 1989. Conference Proceedi
IEEE Pacific Rim Conference on , 1-2 June 1989
Page(s): 301 -305

[Abstract] [PDF Full-Text (384 KB)] **IEEE CNF**

4 **Grasping polyhedral objects with slip**
*Gopalswamy, S.; Fearing, R.S.;*
Robotics and Automation, 1989. Proceedings., 1989 IEEE International Confere
14-19 May 1989

1) Enter a single keyword, phrase, or Boolean expression.
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*Handschumacher, M.D.; Sanfilippo, A.J.; Harrigan, P.; Weyman, A.E.; Levine, R*
Computers in Cardiology 1988. Proceedings. , 25-28 Sept. 1988
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4 **3-D position sensing using a single camera approach**
*Cardillo, J.; Sid-Ahmed, M.A.; Soltis, J.J.;*
Circuits and Systems, 1989., Proceedings of the 32nd Midwest Symposium on , Aug. 1989

Page(s): 325 -328 vol.1

[Abstract] [PDF Full-Text (284 KB)] **IEEE CNF**

5 **From partial derivatives of 3-D density images to ridge lines**
*Monga, O.; Benayoun, S.; Faugeras, O.D.;*
Computer Vision and Pattern Recognition, 1992. Proceedings CVPR '92., 1992 II
Computer Society Conference on , 15-18 June 1992
Page(s): 354 -359

[Abstract] [PDF Full-Text (512 KB)] **IEEE CNF**

6 **Selecting distinctive scene features for landmarks**
*Li, S.; Tsuji, S.;*
Robotics and Automation, 1992. Proceedings., 1992 IEEE International Confere
12-14 May 1992
Page(s): 53 -59 vol.1

[Abstract] [PDF Full-Text (952 KB)] **IEEE CNF**

7 **Determining location and orientation of a labelled cylinder using point estimation algorithm**
*Yuan-Chiuan You; Jiann-Der Lee; Jau-Yien Lee; Chin-Hsing Chen;*
Pattern Recognition, 1992 . Vol.1. Conference A: Computer Vision and Applicati
Proceedings., 11th IAPR International Conference on , 30 Aug.-3 Sept. 1992
Page(s): 354 -357

[Abstract] [PDF Full-Text (260 KB)] **IEEE CNF**

8 **Recognition of multiple objects using geometric hashing techniques**
*Edwards, J.; Shoureshi, R.;*
Decision and Control, 1993., Proceedings of the 32nd IEEE Conference on , 15-1
1993
Page(s): 1617 -1622 vol.2

[Abstract] [PDF Full-Text (480 KB)] **IEEE CNF**

9 **Ratio of infarct subtended volume to surface area by 3-D echocardiogr in vivo measurement of infarct dilation and aneurysm formation**
*King, D.L.; Gopal, A.S.; Schroder, K.M.; Sapin, P.M.; King, D.L., Jr.; Shen, Z.;*
Computers in Cardiology 1993. Proceedings. , 5-8 Sept. 1993
Page(s): 17 -20

[Abstract] [PDF Full-Text (356 KB)] **IEEE CNF**

10 **Differential volume rendering: a fast volume visualization technique i animation**
*Han-Wei Shen; Johnson, C.R.;*
Visualization, 1994., Visualization '94, Proceedings., IEEE Conference on , 17-2: 1994
Page(s): 180 -187, CP20

[Abstract] [PDF Full-Text (640 KB)] **IEEE CNF**

11 **Duality of reconstruction and positioning from projective views**
*Carlsson, S.;*
Representation of Visual Scenes, 1995. (In Conjuction with ICCV'95), Proceedin Workshop on , 24 June 1995
Page(s): 85 -92

[Abstract] [PDF Full-Text (572 KB)] **IEEE CNF**

12 **Tracking 3D position and orientation from 2D sequences using simpl geometry**
*Moore, D.; Hayes, M.;*
Signals, Systems and Computers, 1996. 1996 Conference Record of the Thirtiet Asilomar Conference on , Volume: 1 , 3-6 Nov. 1996
Page(s): 125 -129 vol.1

[Abstract] [PDF Full-Text (440 KB)] **IEEE CNF**

13 **Visual control of an autonomous vehicle using neural networks**
*Young-Cheol Lim; Young-Jae Ryoo; Jong-Kun Park; Eui-Sun Kim; Tae-Gon Kim; Chae-Joo Moon;*
Industrial Electronics, Control, and Instrumentation, 1996., Proceedings of the IEEE IECON 22nd International Conference on , Volume: 2 , 5-10 Aug. 1996
Page(s): 1064 -1069 vol.2

[Abstract] [PDF Full-Text (424 KB)] **IEEE CNF**

14 **A model-based gaze tracking system**
*Stiefelhagen, R.; Jie Yang; Waibel, A.;*
Intelligence and Systems, 1996., IEEE International Joint Symposia on , 4-5 No
Page(s): 304 -310

[Abstract] [PDF Full-Text (728 KB)] **IEEE CNF**

15 **Surface reconstruction using multiple light sources and perspective projection**

*Galo, M.; Tozzi, C.L.;*

Image Processing, 1996. Proceedings., International Conference on , Volume: 1

Sept. 1996

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| - | 29 | 382/154.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/25 11:26 |
| - | 1 | 382/287.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/25 11:18 |
| - | 2 | 382/291.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/25 11:18 |
| - | 0 | 382/298.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/25 11:18 |
| - | 0 | 382/216.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/25 11:18 |
| - | 0 | 345/95.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/25 11:18 |
| - | 56 | 600/$.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/25 11:18 |
| - | 80 | 382/$.ccls. and ((((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same (imag$3)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/25 11:18 |

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|---|---|---|---|---|
| - | 4 | ("4396945" \| "4649504" \| "5227985" \| "5530771").PN. | USPAT | 2003/09/25 12:26 |
| - | 14 | 5828770.URPN. | USPAT | 2003/09/25 12:28 |
| - | 1 | 5828770.pn. and (stereo$7) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/25 15:09 |
| - | 67 | (((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same ((single or one) near5 (imag$3)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/25 16:12 |
| - | 51 | (((((3d or three$1dimension$3 or (three near dimension$3))) same (((position or location) same (orientation or direction)) or pose)) same (mark$3 or dot or feature or character$5 or id or identif$7 or landmark$2 or point$1)) same (color$1 or colour$1 or geometr$4 or euler)) same ((single or one) near3 (imag$3)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/29 13:06 |
| - | 1 | 5751843.pn. | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/25 16:50 |
| - | 5 | ("4748676" \| "4776464" \| "5072294" \| "5285273" \| "5452370").PN. | USPAT | 2003/09/25 17:17 |
| - | 11 | 5751843.URPN. | USPAT | 2003/09/25 17:18 |
| - | 4876 | (3d or three$1dimension$3 or (three near dimension$3)) same ((single or one) near2 (imag$3)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/29 13:08 |
| - | 1373 | (3d or three$1dimension$3 or (three near dimension$3)) with ((single or one) near (imag$3)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/29 13:08 |
| - | 556 | (3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/29 13:09 |
| - | 83 | 382/$.ccls. and ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3))) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/29 13:09 |
| - | 0 | 382/$.ccls. and ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3 and (camera or ccd)))) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/29 13:10 |
| - | 7 | ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3 and (camera or ccd)))) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/29 13:16 |
| - | 10320 | (object or subject) same (indicat$4 or marker or mark$4 or point$1) same ((three or ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3)))) near ("D" or dimension$4)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/29 13:15 |
| - | 4915 | (object or subject) with (indicat$4 or marker or mark$4 or point$1) with ((three or ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3)))) near ("D" or dimension$4)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/29 13:15 |

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|---|---|---|---|---|
| - | 403 | ((object or subject) with (indicat$4 or marker or mark$4 or point$1) with ((three or ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3)))) near ("D" or dimension$4))) with (imag$3 and (camera or ccd)) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/29 13:18 |
| - | 225 | (((object or subject) with (indicat$4 or marker or mark$4 or point$1) with ((three or ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3)))) near ("D" or dimension$4))) with (imag$3 and (camera or ccd))) not (stereo$6) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/29 13:17 |
| - | 6 | ((object or subject) with (indicat$4 or marker or mark$4 or point$1) with ((three or ((3d or three$1dimension$3 or (three near dimension$3)) near3 ((single or one) near (imag$3)))) near ("D" or dimension$4))) with ((single or one) near3 (imag$3 and (camera or ccd))) | USPAT; US-PGPUB; EPO; JPO; IBM_TDB | 2003/09/29 13:18 |